EAST Search History

EAST Search History (Prior Art)

Ref#	Hits	Gearch Query DBs Default Operator		Default Operator	Plurals	Time Stamp	
S67	1550	348/143,211.11,211.99.ccls. and @ad<"20031231"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR ON		2009/09/16 11:01	
S68	1205	348/143,211.11,211.99.ccls. and @ad<"20031231" and (location with time with (sensor or camera or CCD) or (first or second))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	SOCR;		2009/09/16 11:04	
S69	52	348/143,211.11,211.99.ccls. and @ad<"20031231" and (((first or second) near (direction or location)) with (sensor or camera or CCD))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	S-PGPUB; OR ON SPAT; USOCR; PO; JPO; ERWENT;		2009/09/16 11:04	
S70	62	@ad<"20031231" and 348/211.11.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB		ON	2009/09/16 11:05	
S71	8	@adc"20031231" and ((perceiv \$3 with map) with camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	SPAT; USOCR; PRS; EPO; JPO; ERWENT;		2009/09/16 11:08	
S72	1			OR	ON	2009/09/16	

S73	196	"348"/S.cels. and (((perceiv \$30 ar apprehend or behold or comprehend or behold or comprehend or deduce or desery or detect or discern or discover or distinguish or divine or feel or grasp or hear or identify or know or mind or note or notice or observe or realize or recognize or see or sense or smell or spot or taste or touch or understand) with (map or atlas or blueprint or cartograph or chart or delineate)) with camera.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/09/16
S74	69	"348"/S.ccls. and (((perceiv Garden'20031231" and (((perceiv S3 or apprehend or behold or comprehend or deduce or descry or detect or discern or discover or distinguish or divine) with (map or atlas or blueprint or cartograph or chart or delineate)) with camera)		OR	ON	2009/09/16 11:11 2009/09/16 11:13
S75	58	"348"/S.ccls. and @ad<"20031231" and (((perceiv S3 or apprehend or comprehend or detect) with (map or blueprint or cartograph or chart or delineate)) with camera)	31" and (((perceiv do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r chart or do r comprehend (map or blueprint r co			
S76	5	"348"/S.ccls. and @ad<"20031231" and (((perceiv \$3) with (map or blueprint or cartograph or chart or delineate)) with camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/09/16 11:13
S77	60	348/211.9,11.99.ccls. and @ad<"20031231"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/09/16 11:14
S78	6	((STEVEN) near2 (BLUMENFELD)).INV.	US-PGPUB; USPAT	OR	ON	2009/09/16 11:16

EAST Search History (Interference)

Ref#	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S 79		1	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:19

S80	0	(determining first locations for the sensors in the sensor array at a first time to provide first location information).clm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:19
S81	0	(enabling the user to perceive a map related to the entertainment event or venue enabling the user to perceive the first location of one or more of the sensors in the sensor array on the perceived map based on the first location information). clm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:20
S82	0	(determining second locations for the sensors in the sensor array at a second time to provide second location information second locations being different from the first locations second time being after the first time).clm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:20
S83	0	(enabling the user to perceive the second location of the one or more of the sensors in the sensor array on the perceived map based on the second location information).clm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:21
S84	0	(receiving a request from the user identifying a selected position within the perceived map).clm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:21
S86		(managing a sensor array having at least two sensors that are each configured to provide a stream of data units determining first locations for the sensors in the sensor array at a first time to provide first location information enabling the user to perceive a map related to the entertainment event or venue enabling the user to perceive the first location of one or more of the sensors in the sensor array on the perceived map based on the first location information determining	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:27

		second locations for the sensors in the sensor array). clm.				***************************************
887	0	(enabling the user to perceive a map related to the entertainment event or venue enabling the user to perceive the first location of one or more of the sensors in the sensor array on the perceived map based on the first location information determining second locations for the sensors in the sensor array at a second location information, the second location information, the second locations second locations being different from the first locations second time being after the first time enabling the user to perceive the second location of the one or more of the sensors in the sensor array on the sensor array on the second location information receiving a request from the user identifying a selected position within the perceived map./cm.	US-PGPUB; UPAD	WITH	ON	2009/09/16 11:28

9/16/2009 11:30:12 AM C:\Documents and Settings\kwang\My Documents\EAST\Workspaces\10748123.wsp